# **Bunch Arrival Synchronization**



- Arrival time detector overview
- Optical synchronization system using a pulsed reference laser
  - Distribution system
  - Synchronization of laser oscillators
  - Measurement and generation of RF signals
  - Arrival time detector
- Sources for arrival time changes
   Arrival time stabilization at FLASH
- Summary of arrival time detectors

## **ERL** requirements

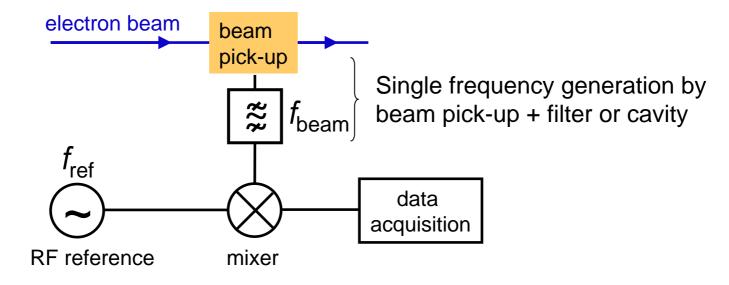


Modes	(A) Hi-flux	(B) Coherence	(C) Small Charge, Short Bunch, Hi- Rep Rate	(D) <sup>3</sup> High Charge, Short Bunch, Lo- Rep Rate
Energy (GeV)	5	5	5	5
Current (mA)	100	25	TBD <sup>1</sup>	0.1
Bunch Charge (pC)	77	19	TBD <sup>1</sup>	1000
Repetition Rate (MHz)	1300	1300	1300	0.1
Geom. Emittance, both Horiz. & Vert. (pm)	30	8	TBD <sup>1</sup>	500
RMS Bunch Length (fs)	2000	2000	<100 <sup>2</sup>	<100 <sup>2</sup>
Relative electron energy spread (x10 <sup>-3</sup> )	0.2	0.2	1	1

In short pulse modes, an electron bunch arrival time stability of 10 fs is required.

#### Arrival time detection by RF methods Simplified principle



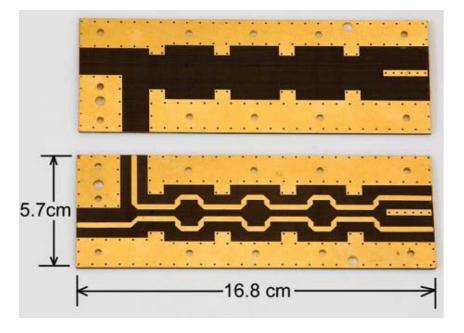


#### Measurement of beam phase relative to RF reference

- + relative simple setup
- + high resolution possible at high frequencies
- + single bunch measurement possible demonstrated at 2 ns bunch spacing (J. Fox et al.)
- long-term stability hard to achieve
  - band pass filter / cavity and mixer tend to drift
  - drift free generation of high frequency reference signal is challenging
- no information on bunch shape

#### Arrival time detection by RF methods PEP-II / ALS / BESSY / PLS system





Planar stripline circuit band-pass filter

- generates 4 cycle output signal at 2856 MHz from a button BPM signal
- Finite time response allows for single bunch detection at small bunch spacings (here: 2 ns)

Single shot resolution: 200 fs.

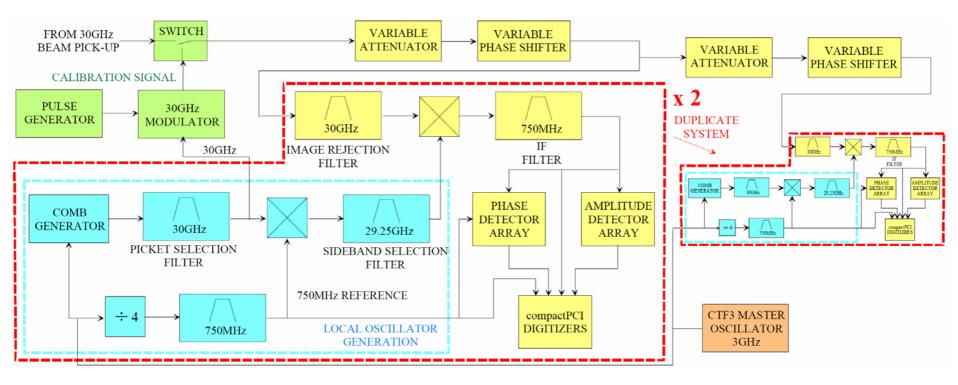
Estimated resolutions for a higher frequency design:

Parameter	3 GHz	10 GHz	30 GHz	]
Channel Noise (rms)	0.8	0.8	0.8	bunch charge: 10 nC
Bunch Charge (C)	1E8	1E8	1E8	· ← · ·
Estimated resolution	0.2 ps	0.06 ps	0.02 ps	ERL: 0.077 nC

Courtesy of J. Fox (SLAC), et al.

#### Arrival time detection by RF methods CLIC system





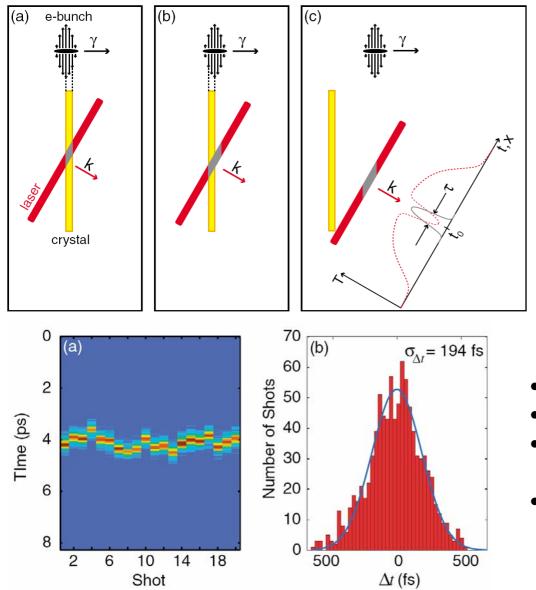
- detection scheme at 30 GHz
- less than 10 fs resolution in 250 MHz bandwidth
- bunch spacing: 333 ps

Courtesy of A. Andersson, J.P.H. Sladen (CERN)

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### Electro-optical arrival time detection: Spatial mapping





Detection of electron arrival time with respect to reference beam.

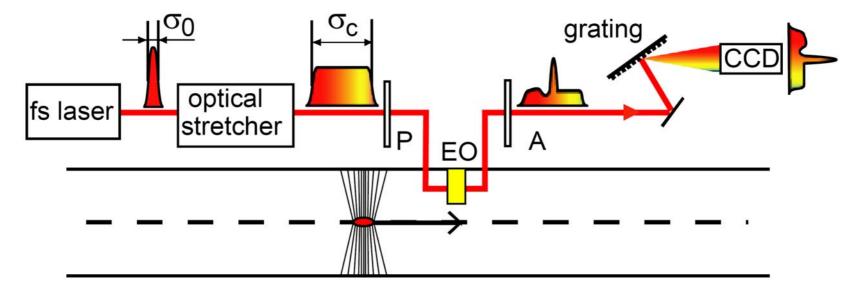
- Mapping of electron bunch profile into polarization of a short laser pulse using an electro-optical crystal.
- Different arrival times correspond to different spatial positions of the laser pulse.
- 30 fs resolution for bunch centroid
- single bunch measurement
- sample rate limited by readout system (and laser repetition rate)
- Bunch profile information available

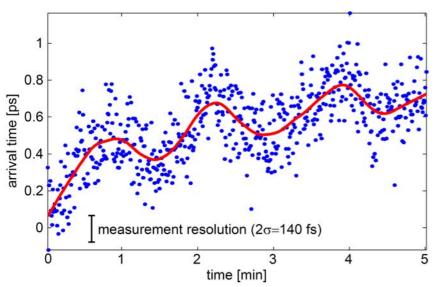
Courtesy of A. Cavalieri

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#### Electro-optical arrival time detection: Spectral decoding







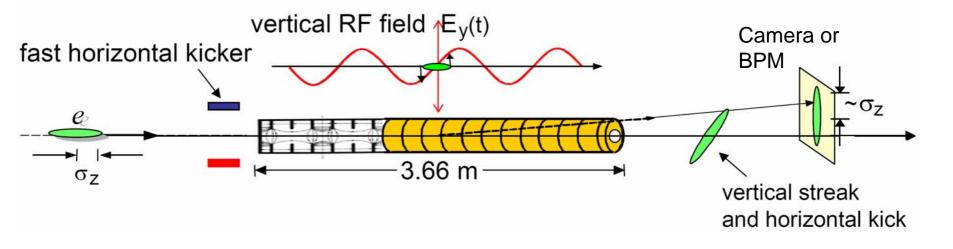
 Mapping of electron bunch profile into optical spectrum of a broad-band laser pulse using an electro-optical crystal.

Similar performance as previous scheme.

Courtesy of G. Berden et al. (FELIX)

Arrival time measurement with a transverse deflecting structure





Measurement of the bunch arrival time with respect to the RF field in the cavity

- + highest temporal resolution of the discussed methods (sub 20 fs within the longitudinal profile)
- + single shot detection possible
- + small bunch spacing possible when paired with BPM readout system
- Streaked bunches are lost
- o Knowledge of the timing of the cavity RF field determines arrival time resolution

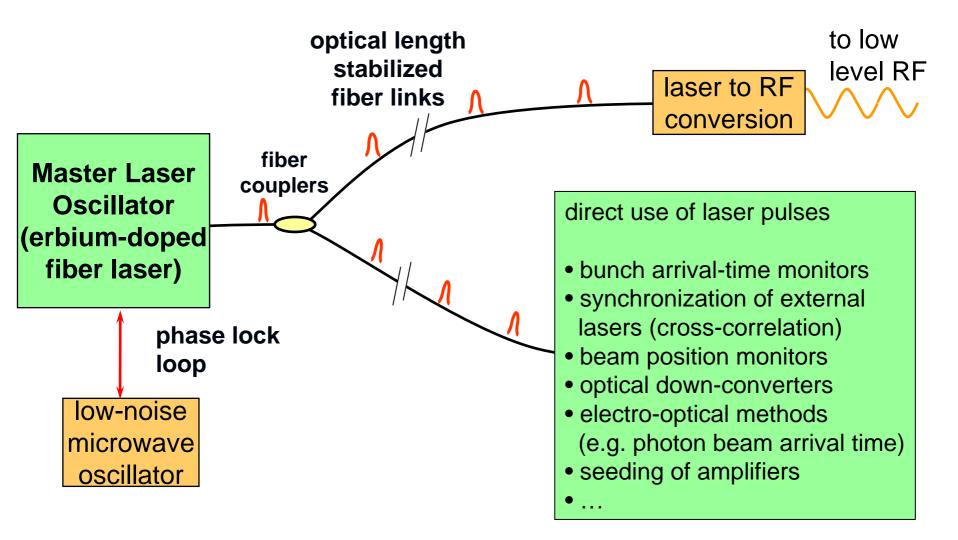
## "Synchronization" of arrival time monitors



- "Single frequency detection"
  - provide stable RF signal with respect to reference
  - phase detection of RF signal with respect to reference
- Electro-optical methods with external lasers
  - synchronize laser to reference
- Transverse deflecting cavity
  - provide stable RF signal with respect to reference
  - phase detection of RF signal with respect to reference

# Layout of the optical synchronization system at FLASH



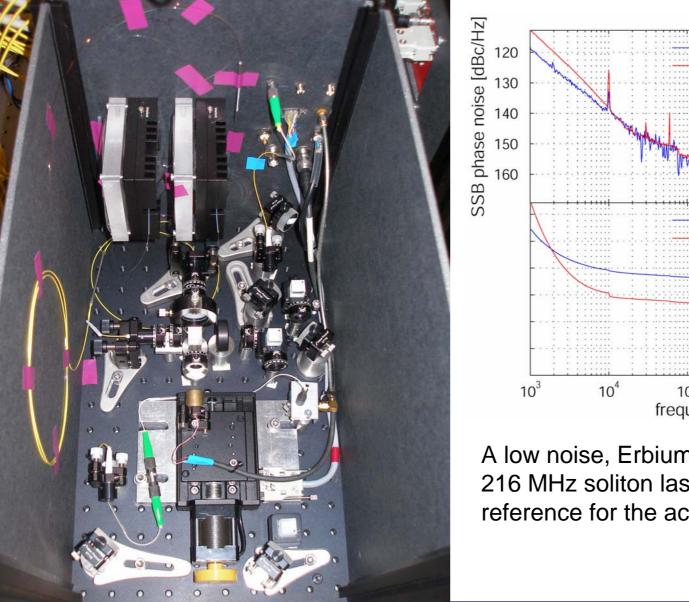


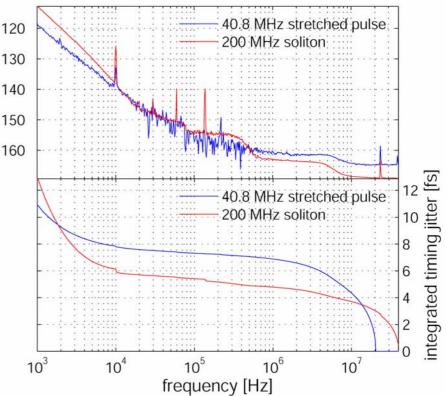
Development in collaboration with MIT (F.X. Kaertners group)

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### The fiber laser system





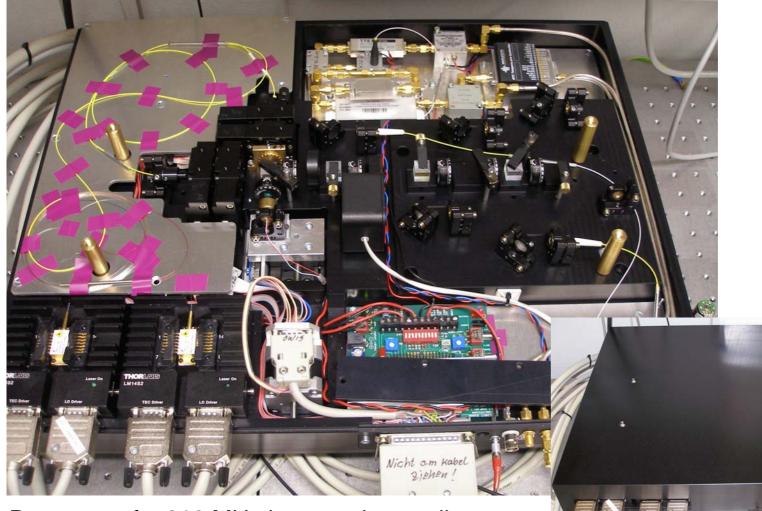


A low noise, Erbium-doped, modelocked, 216 MHz soliton laser is used as the timing reference for the accelerator.

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### First prototype of a 216 MHz laser



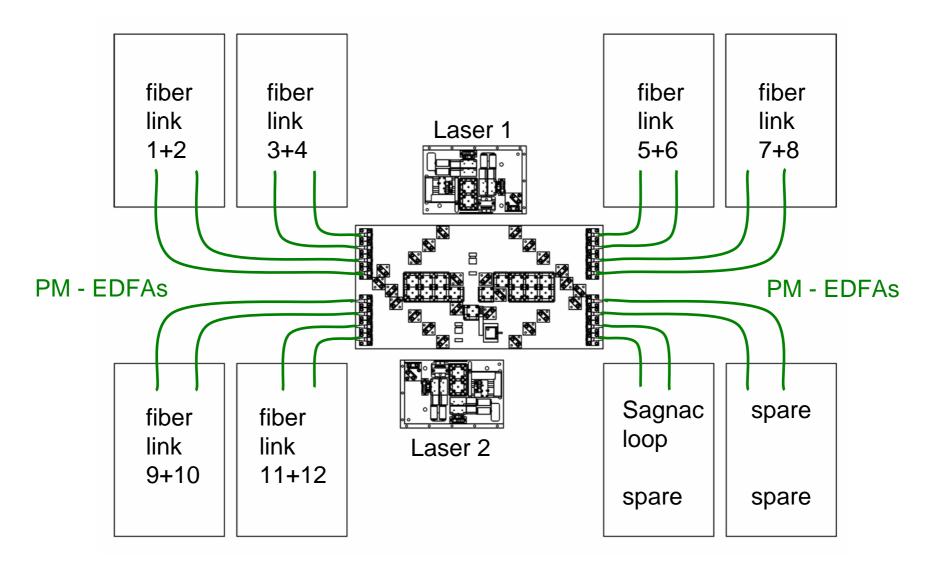


Prototype of a 216 MHz laser and a small distribution unit. The second iteration is on its way.

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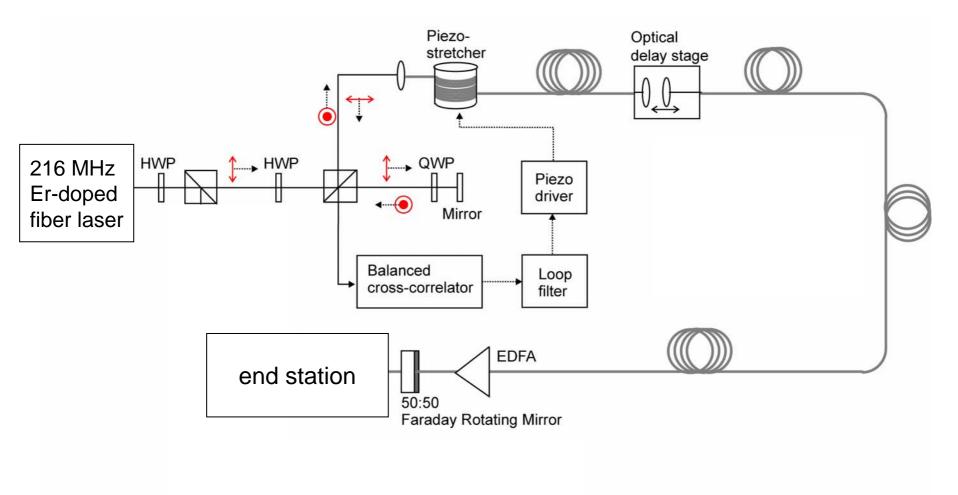
#### Laser distribution unit Schematic layout





#### Fiber link stabilization: Schematic setup

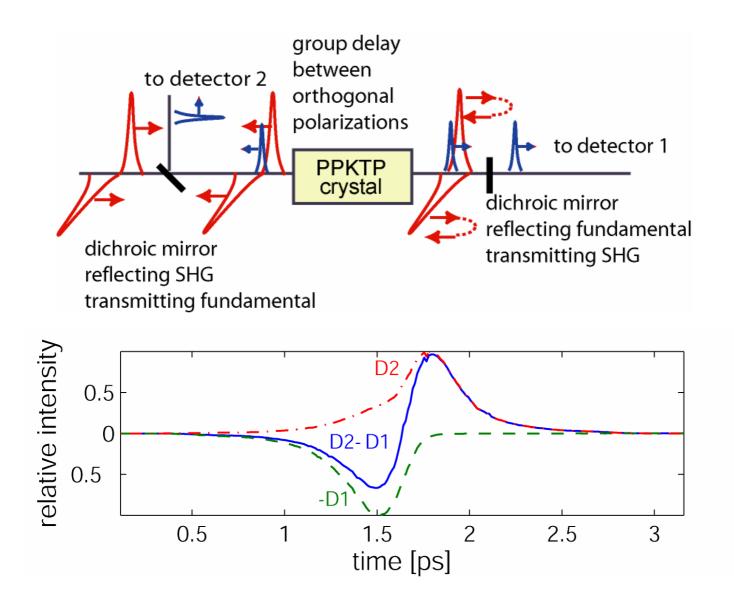




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#### Fiber link stabilization: Balanced optical cross-correlator

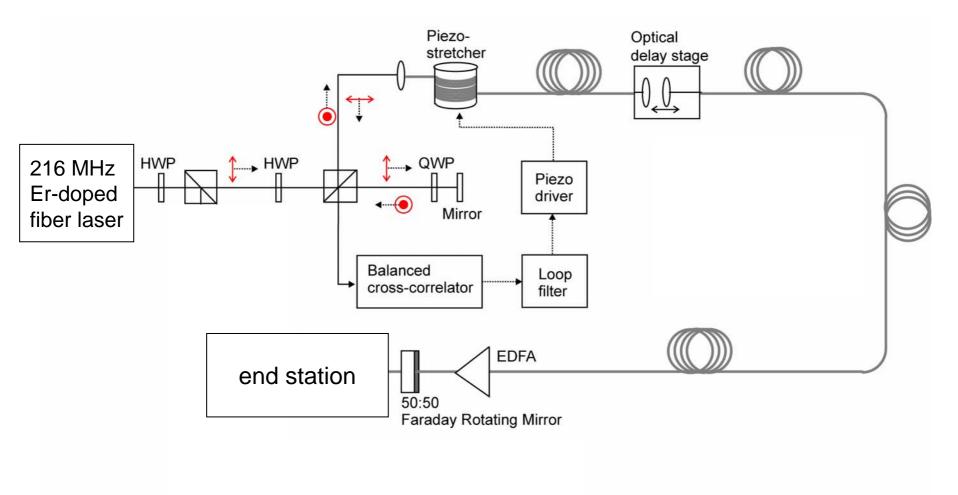




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#### Fiber link stabilization: Schematic setup

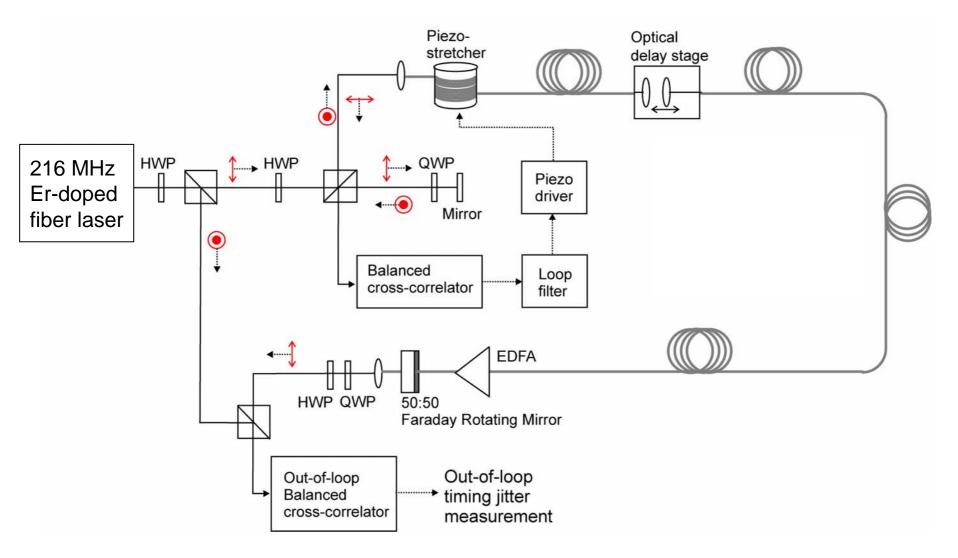




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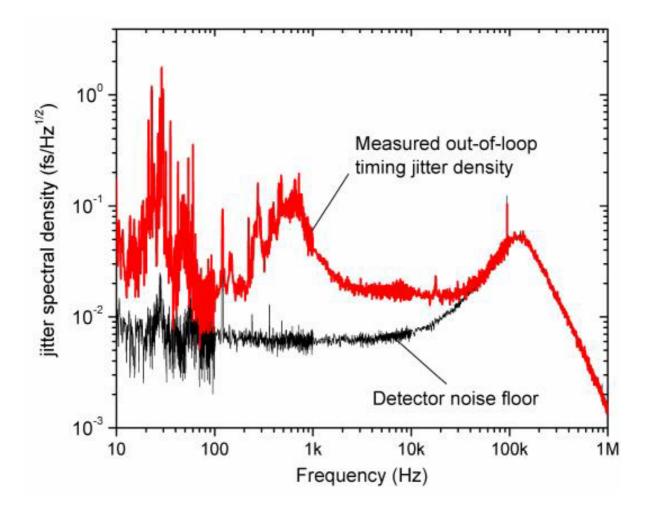
#### Fiber link stabilization: Schematic setup to determine fiber link stability





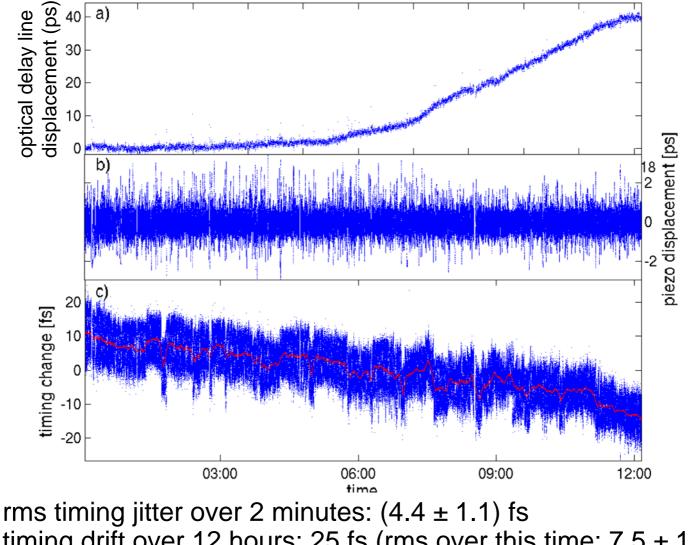
#### Fiber link stabilization Frequency distribution of fiber link timing changes





#### Fiber link stabilization Long term stability



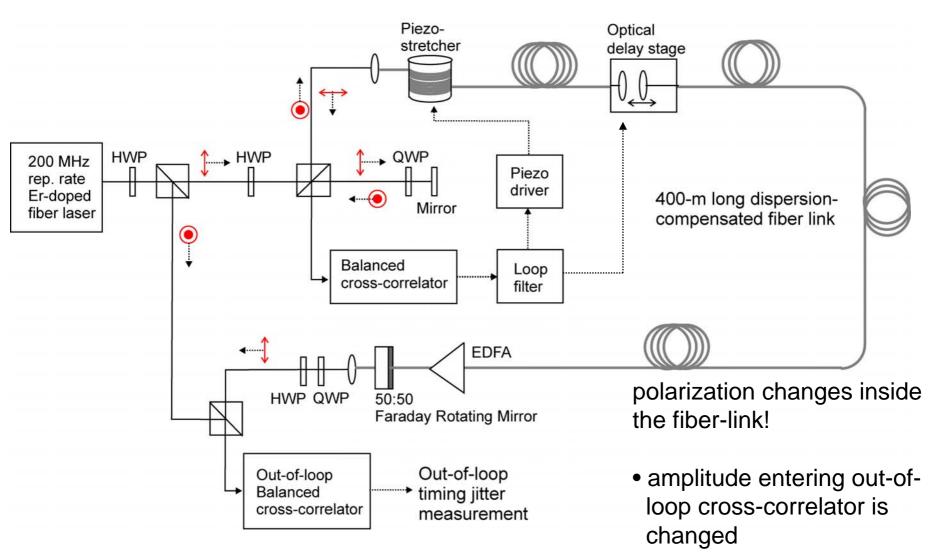


timing drift over 12 hours: 25 fs (rms over this time:  $7.5 \pm 1.8$  fs) measurement bandwidth: 200 kHz

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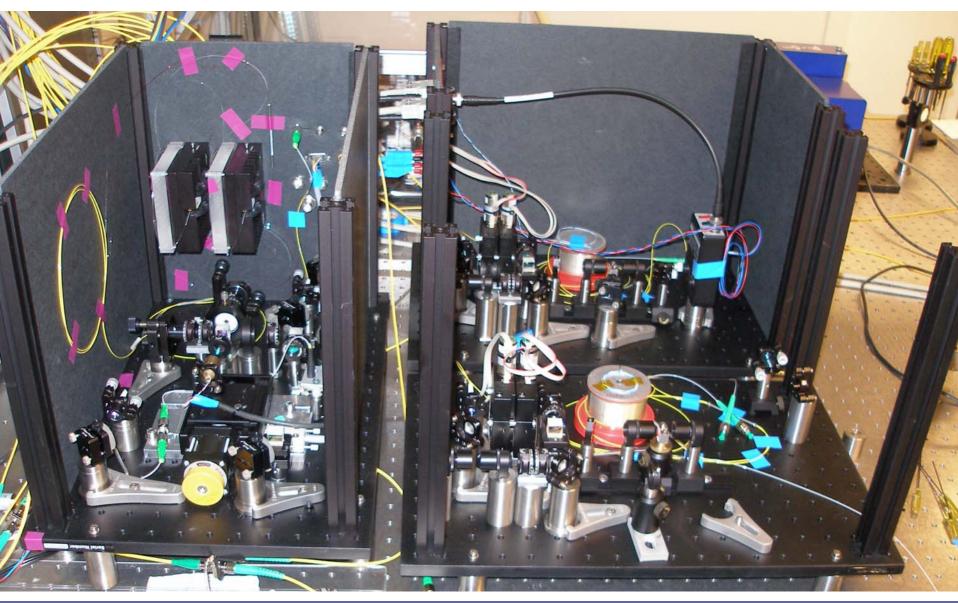
#### Fiber link stabilization Timing drift a measurement artifact?





## Prototypes of master laser and fiber link stabilization

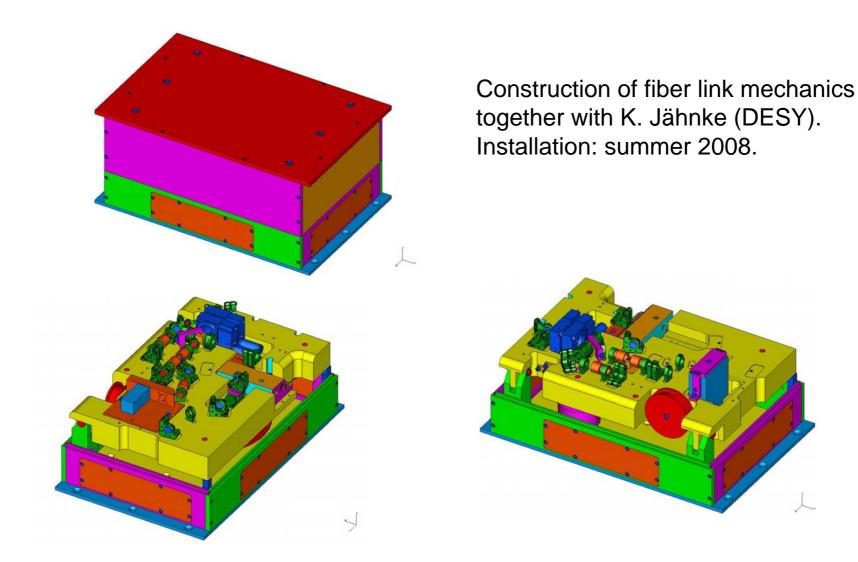




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#### Fiber link stabilization Mechanical design

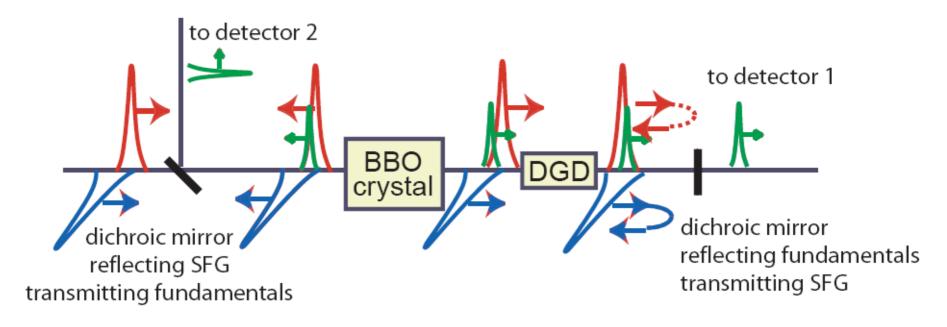




#### Locking of external lasers Scheme of optical cross-correlator



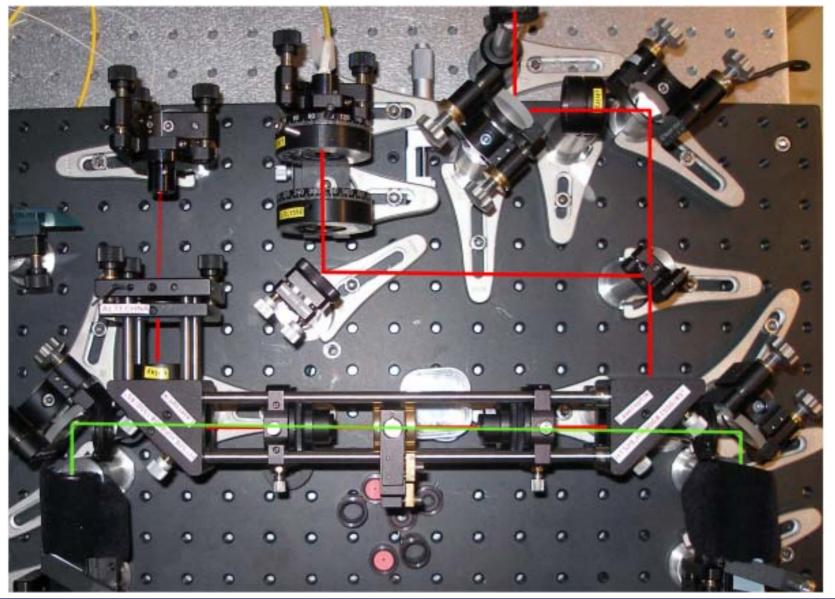
A similar scheme as for the fiber link cross-correlator will be used:



DGD: differential group delay

#### Locking of external lasers First setup

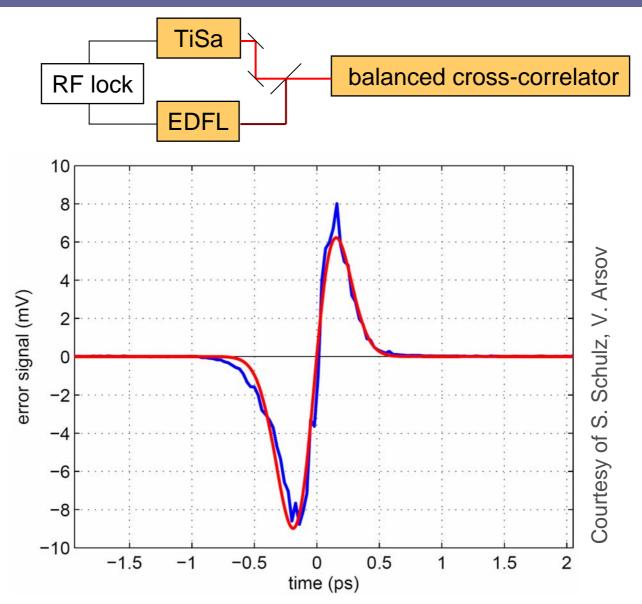




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#### Locking of external lasers First signal





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#### Laser to RF conversion Possible schemes

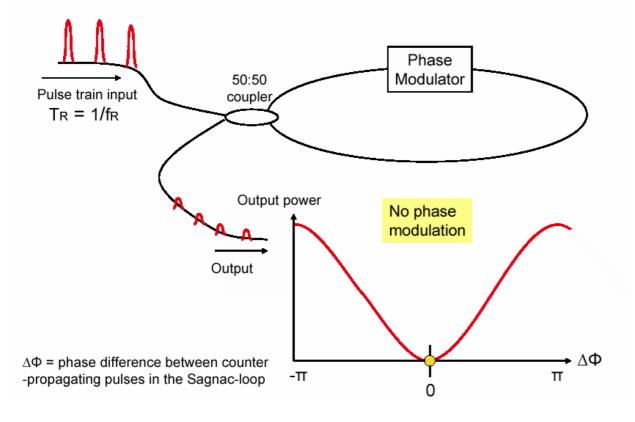


#### laser pulses **Optical division of** AOM / distributed frequency EOM f<sub>rep</sub> / n f<sub>rep</sub> modulation voltage $f = n^* f_{rep}$ laser pulses **Direct conversion with PD** PD **BPF** - temperature drifts AM to PM conversion\* f<sub>rep</sub> - noise limitation due to low power $f = n^* f_{rep}$ in spectral line of PD output $f = n^* f_{rep}$ **Injection Locking** resonator laser pulses PD - temperature drifts of PD phase shifter – AM to PM conversion of PD\* + DRO determines high frequency f<sub>rep</sub> noise Low noise DRO + entire photo detector signal used $(f = n^* f_{rep})$ (\*) typical AM to PM conversion: 1-10ps/mW

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# RF extraction and measurement with a Sagnac loop interferometer

Phase detection in the optical domain:

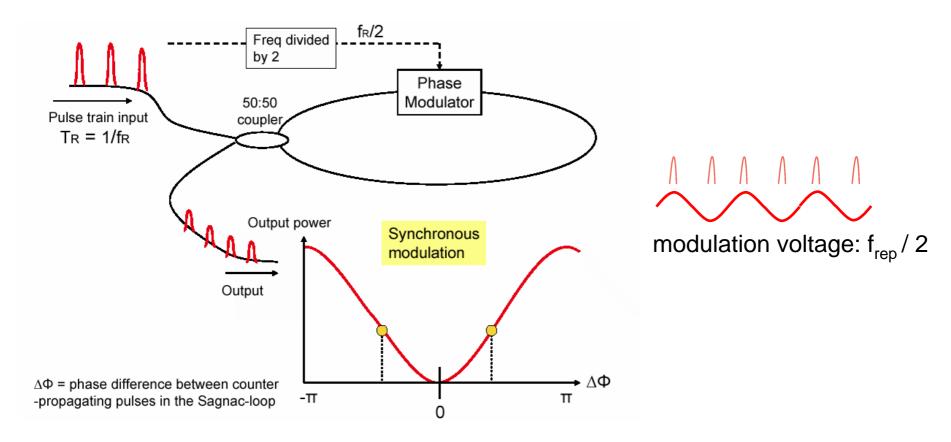


Courtesy of J. Kim (MIT)

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# RF extraction and measurement with a Sagnac loop interferometer

Phase detection in the optical domain:



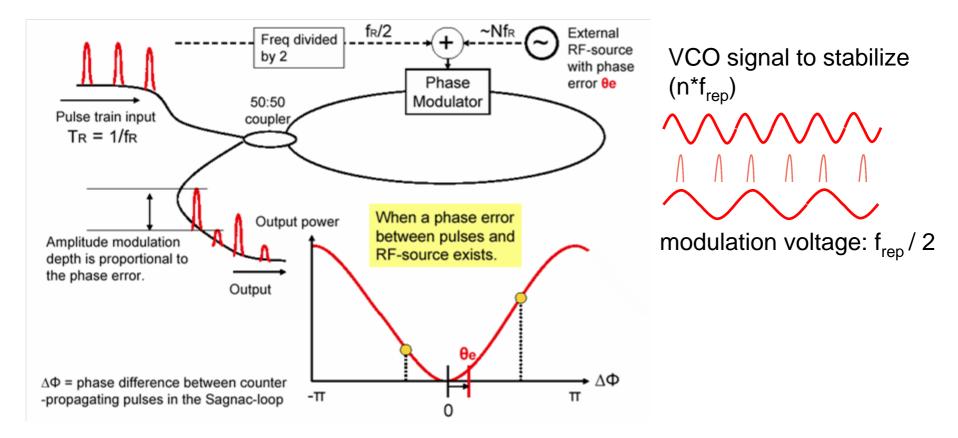
Courtesy of J. Kim (MIT)

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# RF extraction and measurement with a Sagnac loop interferometer



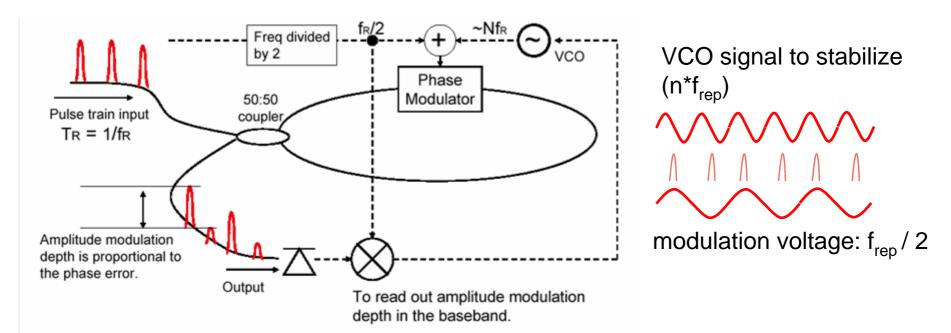
#### Phase detection in the optical domain:



Courtesy of J. Kim (MIT)



#### Phase detection in the optical domain:



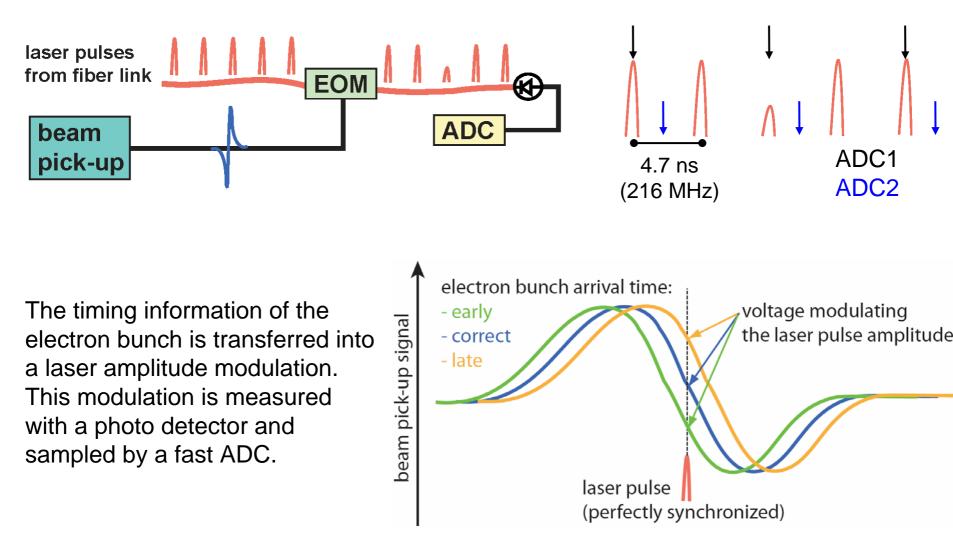
First results with a DRO (dielectric resonance oscillator) frequency of 10 GHz are very promising (6.8 fs over 10 h). Next step: Transition to 1.3 GHz DRO.

Courtesy of J. Kim (MIT)

### Bunch arrival time monitor (BAM) Detection principle

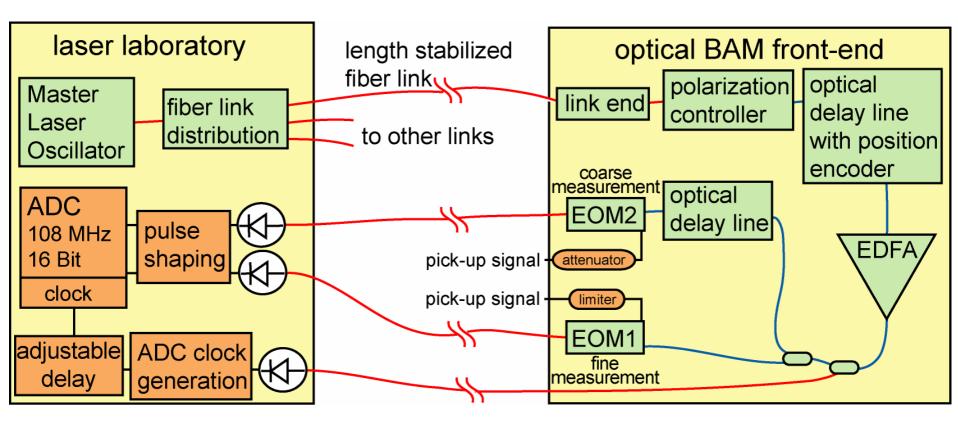


sampling times of ADCs



#### Bunch arrival time monitor (BAM) Schematic setup



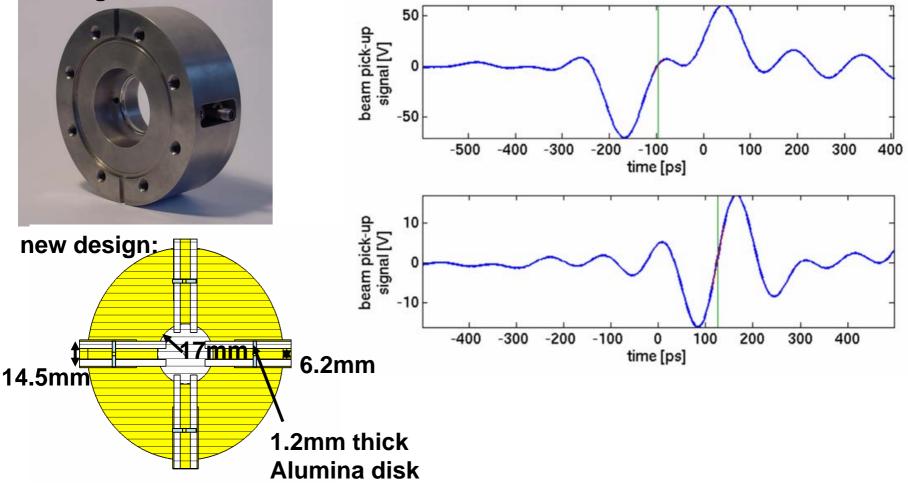


### Bunch arrival time monitor (BAM) Beam pick-up



During last summer, a new beam pick-up (design: K. Hacker) was installed instead of ring electrodes to improve the pick-up performance.

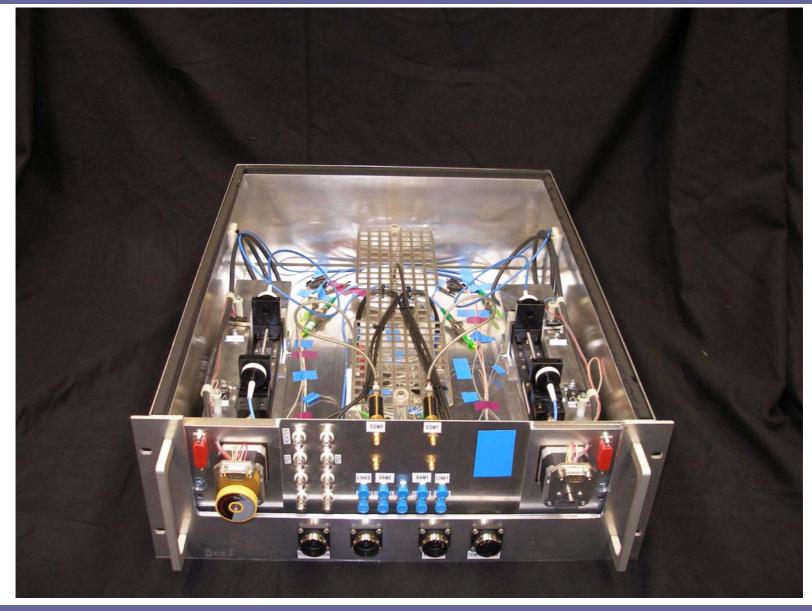
#### old ring electrode:



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BAM

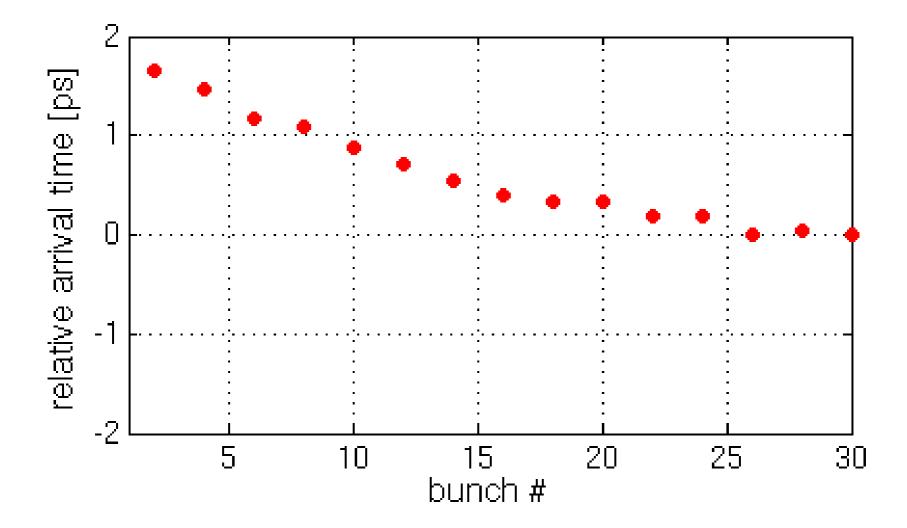




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# Bunch arrival time monitor (BAM) shot-to-shot fluctuations and intra bunch train pattern

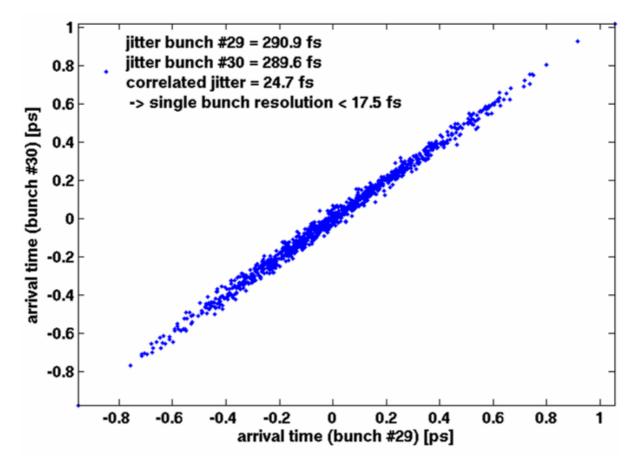




#### Bunch arrival time monitor (BAM) BAM resolution



An upper limit for the BAM resolution can be estimated by correlating the arrival time of two adjacent bunches in the bunch train:



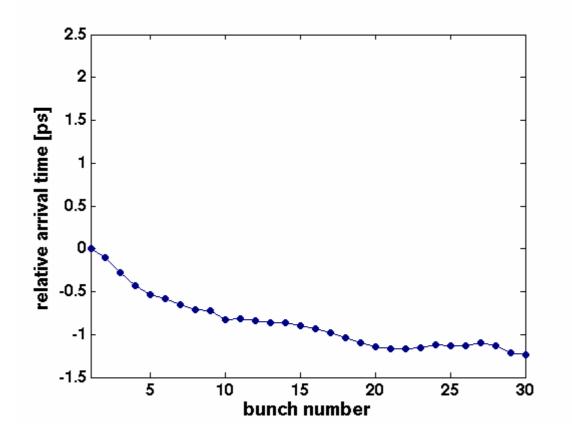
The resolution estimated from the laser amplitude noise and the slope steepness is about 5-6 fs.

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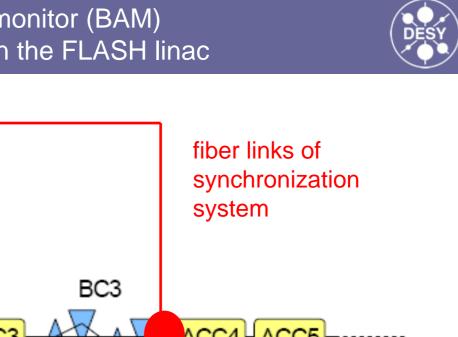
Bunch arrival time monitor (BAM) Arrival time manipulation over the bunch train

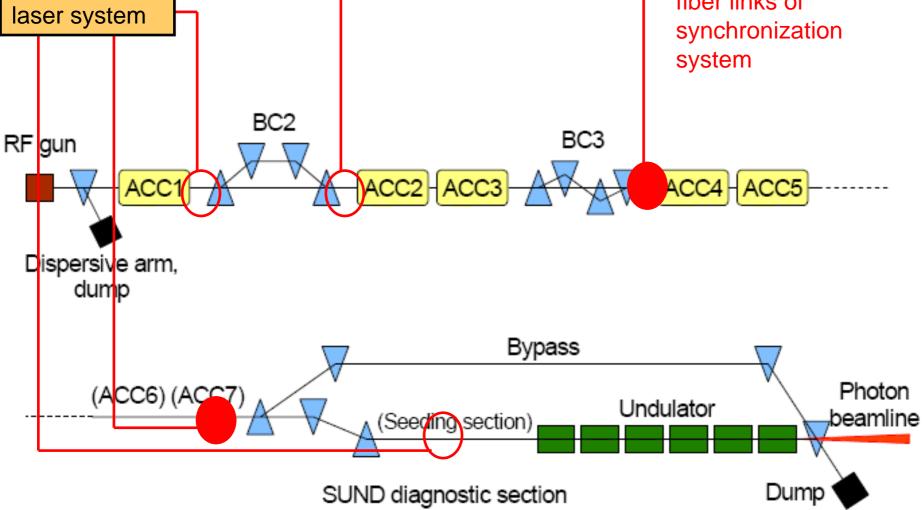


Goal: generate and compensate arrival time slopes with the beam loading amplitude of ACC1



Bunch arrival time monitor (BAM) Positions of the BAMs in the FLASH linac





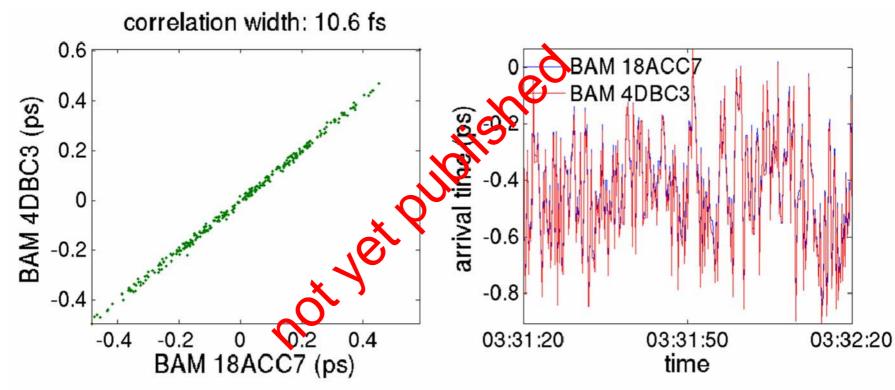
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Synch Lab

with master

### Arrival time correlation between two BAMs





Arrival time measurement with two BAMs, separated by 60 m drift space. Arrival time difference contains:

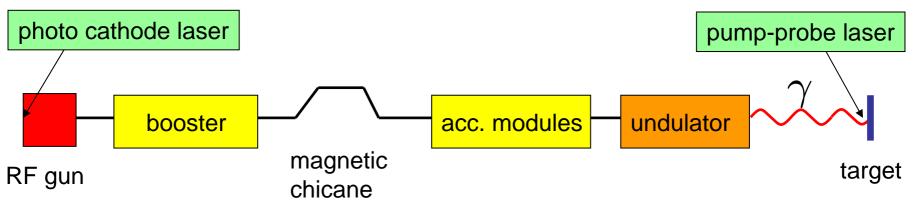
- high frequency laser noise (~1.7 MHz 216 Mhz)
- two fiber link stabilizations
- two BAMs

Single bunch resolution of entire measurement chain: 7.5 fs (rms) 300 shots in 60 seconds

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# Timing changes in a FEL



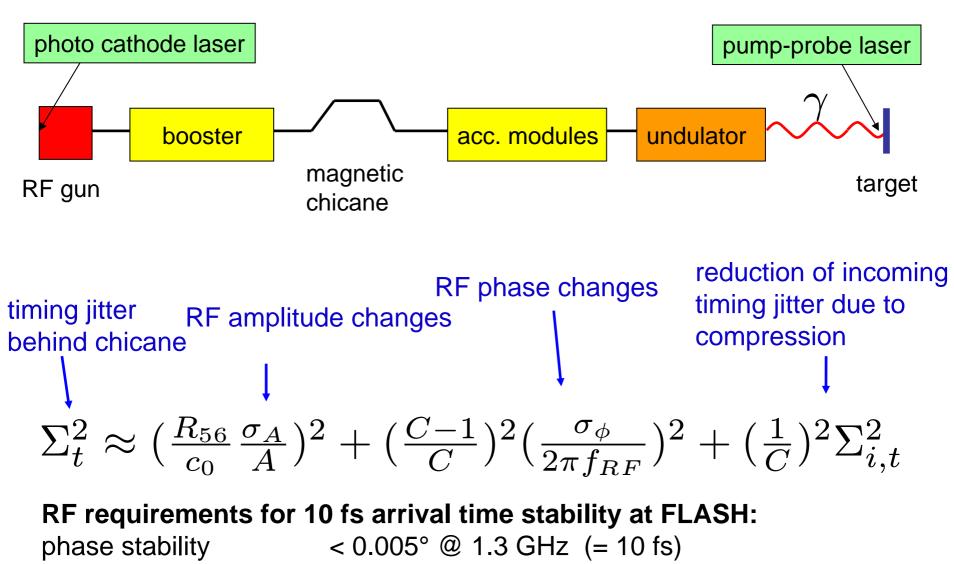


#### Main sources for arrival-time changes of the FEL radiation

- arrival-time of the photo cathode laser pulses
- phase of the RF gun
- amplitude and phase of booster module
- arrival-time of potential seed lasers

### Timing changes in a FEL

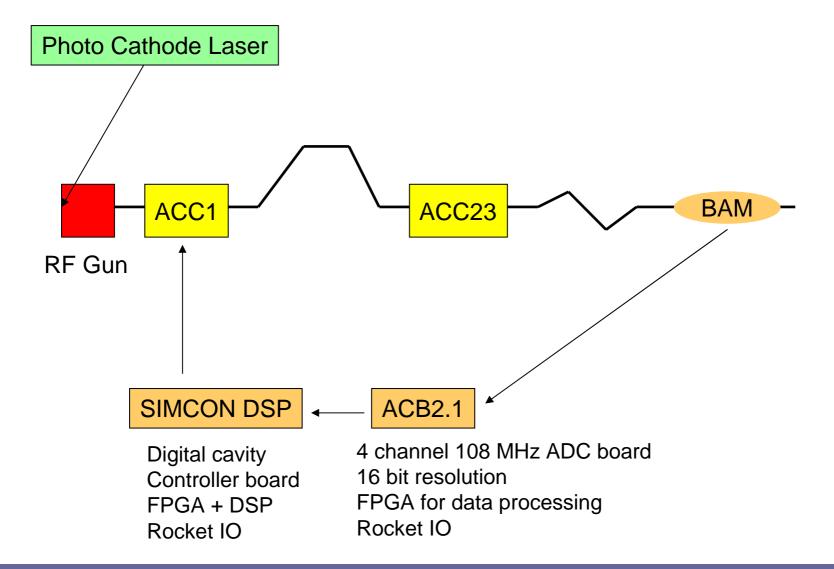




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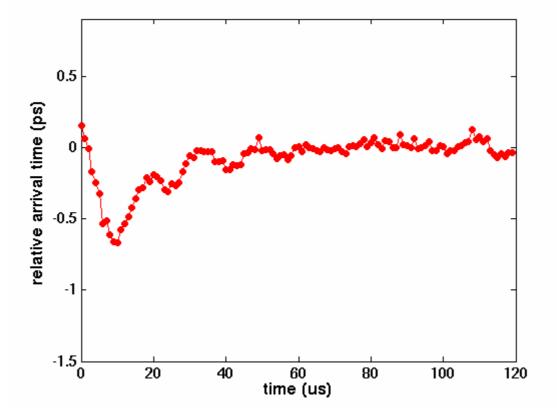
amplitude stability  $< 1.6 * 10^{-5}$ 





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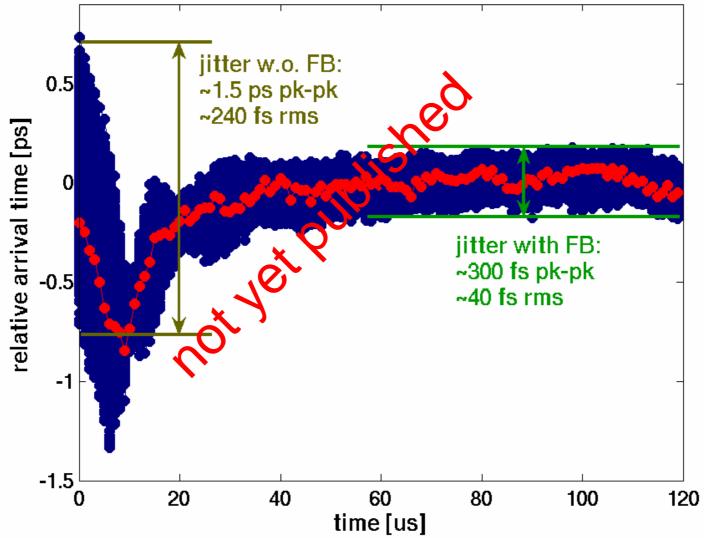




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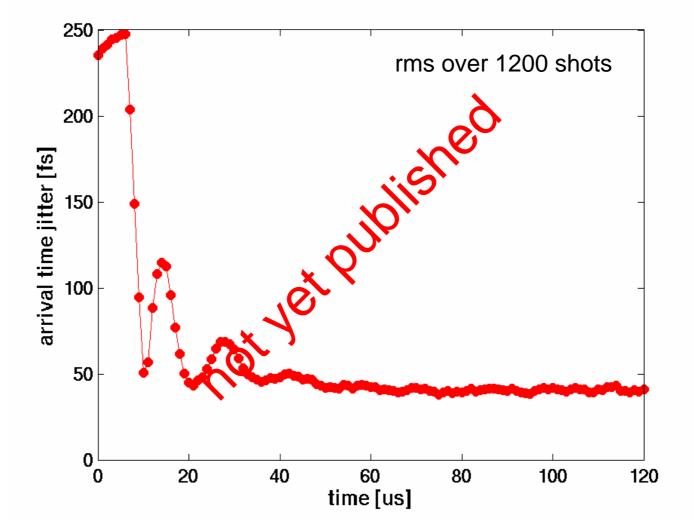






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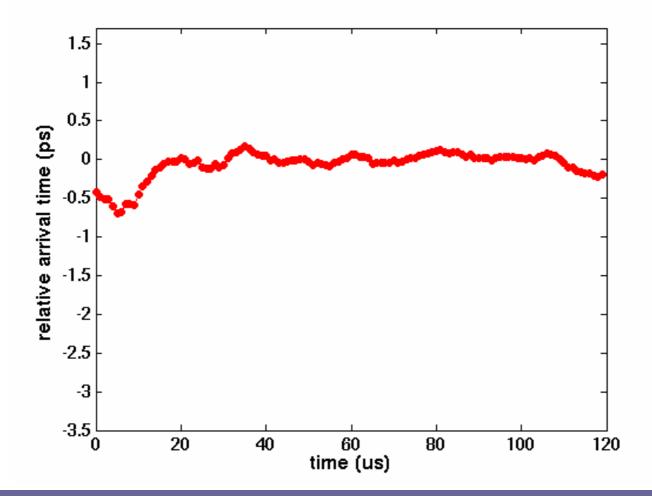




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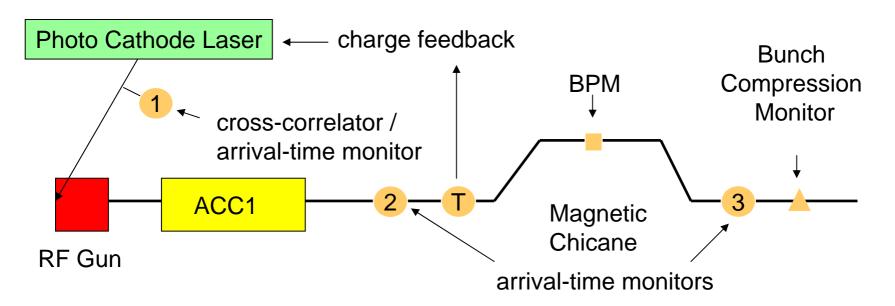
Generation of well defined arrival time slopes over the bunch train: (this allows complete pump-probe experiments within a single bunch train)



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# Outlook: complete longitudinal feedback





#### Detection of main arrival-time jitter sources

- Arrival time of photo cathode laser pulses (CC / 1<sup>st</sup> arrival time monitor)
- Phase of RF gun (difference between 1<sup>st</sup> and 2<sup>nd</sup> arrival time monitor)
- Amplitude of ACC1 (BPM in magnetic chicane)
- Phase of ACC1 (Bunch Compression Monitor)
- Arrival time of pump-probe lasers (cross-correlation with timing system)

### Summary of bunch arrival time detectors



	measurement bandwidth			
	RF mixing	"BAM"	"EO"	TDS
single shot	yes	yes	yes	yes
sample rate	GHz	~200 MHz	~10 – 100 kHz	GHz
pros	<ul> <li>no optics</li> <li>simple setup</li> <li>easy and fast data processing</li> </ul>	<ul> <li>high resolution</li> <li>easy and fast data processing</li> <li>absolute reference</li> <li>drift free</li> </ul>	<ul> <li>high resolution</li> <li>profile information</li> <li>drift free</li> </ul>	-highest resolution profile information
cons	<ul> <li>may drift</li> <li>single shot resolution</li> <li>no profile infos</li> </ul>	<ul> <li>no profile infos</li> <li>small bunch</li> <li>spacing requires</li> <li>fast pick-up</li> </ul>	<ul> <li>complicated</li> <li>slow data acquisition</li> <li>data processing</li> </ul>	-expensive -invasive -may drift
develop. for ERL	- pick-up - drifts	- pick-up	<ul><li>fast detector</li><li>data processing</li></ul>	





- Four different schemes for the arrival time detection were discussed. None of these schemes meets all ERL requirements (i.e. 1.3 GHz data acquisition, low bunch charge).
- The reference signal and its distribution go hand in hand with the arrival-time detection.
- The timing stability of a machine depends sensitively on the design of the bunch compressor scheme.

# **Contributing People**





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# Thank you for your attention!

